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negative slope within the specified speed range if the negative motion is not greater than 10 percent of total control travel.

[Amdt. 29-24, 49 FR 44436, Nov. 6, 1984]

§ 29.175 Demonstration of static longitudinal stability.

- (a) Climb. Static longitudinal stability must be shown in the climb condition at speeds from 0.85 V_Y , or 15 knots below V_Y , whichever is less, to 1.2 V_Y or 15 knots above V_Y , whichever is greater, with—
 - (1) Critical weight:
 - (2) Critical center of gravity;
 - (3) Maximum continuous power;
 - (4) The landing gear retracted; and
 - (5) The rotorcraft trimmed at V_{Y} .
- (b) Cruise. Static longitudinal stability must be shown in the cruise condition at speeds from 0.7 V_H or 0.7 V_{NE} , whichever is less, to 1.1 V_H or 1.1 V_{NE} , whichever is less, with—
 - (1) Critical weight;
 - (2) Critical center of gravity;
- (3) Power for level flight at 0.9 V_H or 0.9 V_{NE} whichever is less;
- (4) The landing gear retracted, and
- (5) The rotorcraft trimmed at 0.9 V_{H} or 0.9 V_{NE} , whichever is less.
- (c) Autorotation. Static longitudinal stability must be shown in autorotation at airspeeds from 0.5 times the speed for minimum rate of descent, or 0.5 times the maximum range glide speed for Category A rotorcraft, to $V_{\rm NE}$ or to 1.1 $V_{\rm NE}$ (power-off) if $V_{\rm NE}$ (power-off) is established under §29.1505(c), and with—
 - (1) Critical weight;
 - (2) Critical center of gravity;
 - (3) Power off;
 - (4) The landing gear—
 - (i) Retracted; and
 - (ii) Extended: and
- (5) The rotorcraft trimmed at appropriate speeds found necessary by the Administrator to demonstrate stability throughout the prescribed speed range.
- (d) Hovering. For helicopters, the longitudinal cyclic control must operate with the sense, direction of motion, and position as prescribed in §29.173 between the maximum approved rearward speed and a forward speed of 17 knots with—
 - (1) Critical weight;
 - (2) Critical center of gravity;

- (3) Power required to maintain an approximate constant height in ground effect:
 - (4) The landing gear extended; and
- (5) The helicopter trimmed for hovering.

(Secs. 313(a), 601, 603, 604, and 605 of the Federal Aviation Act of 1958 (49 U.S.C. 1354(a), 1421, 1423, 1424, and 1425); and sec. 6(c), Dept. of Transportation Act (49 U.S.C. 1655(c)))

[Doc. No. 5084, 29 FR 16150, Dec. 3, 1964, as amended by Amdt. 29–3, 33 FR 966, Jan. 26, 1968; Amdt. 29–12, 41 FR 55471, Dec. 20, 1976; Amdt. 29–15, 43 FR 2327, Jan. 16, 1978; Amdt. 29–24, 49 FR 44436, Nov. 6, 1984]

§ 29.177 Static directional stability.

Static directional stability must be positive with throttle and collective controls held constant at the trim conditions specified in §29.175 (a), (b), and (c). Sideslip angle must increase steadily with directional control deflection for sideslip angles up to $\pm 10^{\circ}$ from trim. Sufficient cues must accompany sideslip to alert the pilot when approaching sideslip limits.

[Amdt. 29–24, 49 FR 44436, Nov. 6, 1984]

§ 29.181 Dynamic stability: Category A rotorcraft.

Any short-period oscillation occurring at any speed from $V_{\rm Y}$ to $V_{\rm NE}$ must be positively damped with the primary flight controls free and in a fixed position.

[Amdt. 29-24, 49 FR 44437, Nov. 6, 1984]

GROUND AND WATER HANDLING CHARACTERISTICS

§29.231 General.

The rotorcraft must have satisfactory ground and water handling characteristics, including freedom from uncontrollable tendencies in any condition expected in operation.

§ 29.235 Taxiing condition.

The rotorcraft must be designed to withstand the loads that would occur when the rotorcraft is taxied over the roughest ground that may reasonably be expected in normal operation.

§29.239 Spray characteristics.

If certification for water operation is requested, no spray characteristics